

Tensors

Remember Maxwell's equations in matter!

$$\begin{aligned} \vec{\nabla} \cdot \vec{D} &= 4\pi\rho \\ \vec{\nabla} \times \vec{H} - \frac{1}{c} \frac{\partial \vec{D}}{\partial t} &= \frac{4\pi}{c} \vec{J} \\ \vec{\nabla} \times \vec{E} + \frac{1}{c} \frac{\partial \vec{B}}{\partial t} &= 0 \\ \vec{\nabla} \cdot \vec{B} &= 0 \end{aligned}$$

(1) Maxwell originally wrote out each component of these equations [~~8~~ equations in all]. Vector notation helps a lot. Other equations involve tensors: where vectors have one index E_i , tensors can have two or more ϵ_{ij} , C_{ijkl} , ...

(2) We can write Maxwell's equations in a more modern ^{"tensor"} notation!

$$\partial_i D_i = 4\pi\rho \quad \left\{ \begin{array}{l} \partial_i = \partial/\partial x_i \\ \text{Einstein convention } x_i y_i = \sum_{i=1}^3 x_i y_i \\ \text{drop summation sign} \end{array} \right.$$

$$\epsilon_{ijk} \nabla_j H_k - \frac{1}{c} \partial_0 D_i = \frac{4\pi}{c} J_i \quad \left\{ \begin{array}{l} \partial_0 = \frac{\partial}{\partial t} \text{ (high energy)} \\ \text{Roman index } 1, 2, 3 \\ \text{Greek } 0, 1, 2, 3 \text{ (high energy)} \end{array} \right.$$

$$\epsilon_{ijk} = \begin{cases} 0 & \text{any index repeats} \\ 1 & \epsilon_{123}, \epsilon_{231}, \epsilon_{312} \\ -1 & \epsilon_{132}, \epsilon_{321}, \epsilon_{213} \end{cases} \quad \begin{array}{l} \epsilon_{ijk} = \text{Totally antisymmetric} \\ \text{tensor in three indices} \\ = \text{Levi-Civita tensor} \end{array}$$

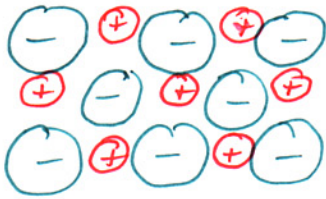
Exercise: Write the other two in modern notation

$$\epsilon_{ijk} \partial_j E_k + \frac{1}{c} \partial_0 B_i = 0 \quad \partial_i B_i = 0$$

(3) What is \vec{D} ?

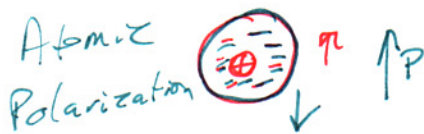
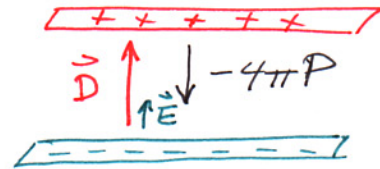
$$\vec{E} \uparrow \quad \uparrow \vec{D}$$

Vacuum: $\vec{D} = \vec{E}$



NaCl

Na shift up
Cl shift down
+ ↑
- ↓



Both cases,
net polarization
charge moves up
 $P \uparrow$

Equivalent to
charge layer on
top & bottom

In matter, \vec{E} is the electric field averaged over the crystal unit cell. It includes a component $-4\pi\vec{P}$ due to the polarization of the crystal.

$$\vec{D} = \vec{E} + 4\pi\vec{P}$$

$$= \epsilon \vec{E}$$

MKS: $\vec{D} = \vec{E} - \frac{\vec{P}}{\epsilon_0}$

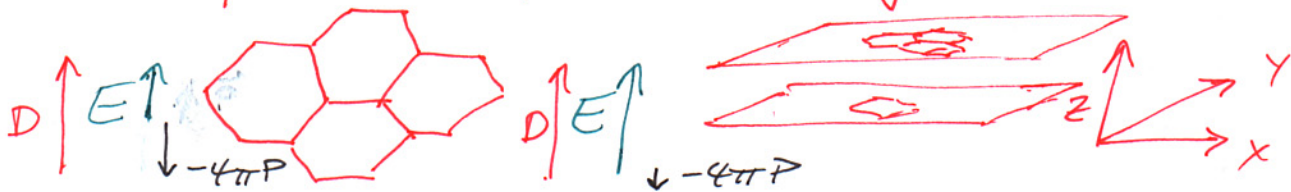
where ϵ is the dielectric constant. Also,

$$P = \alpha E$$

where α is the polarizability, $\epsilon = 1 + 4\pi\alpha$

(4) Dielectric constant ϵ (and α) are tensors, for complex crystals.

Graphite: layers of hexagons



Polarizability (probably) much higher in the plane than perpendicular to planes

$$\alpha_{ij} = \begin{pmatrix} (\text{Big}) & 0 & 0 \\ 0 & (\text{Big}) & 0 \\ 0 & 0 & (\text{small}) \end{pmatrix}$$

$$D_i = \epsilon_{ij} E_j$$

$$P_i = \alpha_{ij} E_j$$

$$= \sum_{j=1}^3 \alpha_{ij} E_j$$

$$= \underset{\uparrow}{\alpha} \cdot \vec{E}$$

Matrix application
to vector

Other Tensors

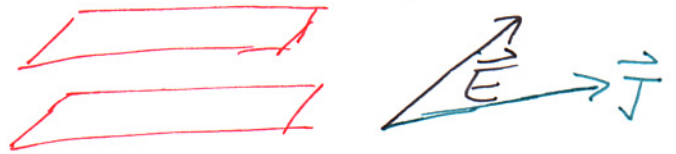
Conductivity

$$\vec{j}_m = \sigma_{mn} E_n$$

can be asymmetric in magnetic field: Hall effect

Graphite $\sigma = \begin{pmatrix} \text{Big} & 0 & 0 \\ 0 & \text{Big} & 0 \\ 0 & 0 & \text{small} \end{pmatrix}$

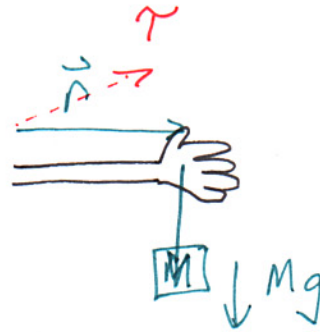
Moment of Inertia (Feynman...)



Notice: \vec{j}, \vec{E} not parallel in general

Torque?

$$\vec{\tau} = \vec{r} \times \vec{F}$$



What is the deep inner meaning of $\vec{\tau}$ pointing into the board?

Right-hand rule convention?

Tensor Notation

$$\tau_i = \epsilon_{ijk} r_j F_k = \frac{1}{2} \epsilon_{ijk} (r_j F_k - r_k F_j)$$

$$= \frac{1}{2} \epsilon_{ijk} \begin{pmatrix} 0 & \tau_z & \tau_y \\ -\tau_z & 0 & \tau_x \\ \tau_y & \tau_x & 0 \end{pmatrix}$$

Torque is "really" an antisymmetric 3×3 matrix! In three

dimensions, we use ϵ_{ijk} to change it into a vector.

$$\det M = \epsilon_{ijk} \epsilon_{lmn} M_{il} M_{jm} M_{kn}$$

$$(M \cdot N)_{ik} = M_{ij} N_{jk}$$